

BINDURA UNIVERSITY OF SCIENCE EDUCATION
FACULTY OF SCIENCE EDUCATION
DEPARTMENT OF ENGINEERING
AND PHYSICS
Bachelor of Science Honours Degree in Electronic Engineering
EEE2209/EEE3205 - CONTROL ENGINEERING []

Time Allowed: 3 Hours

Total Marks: 100

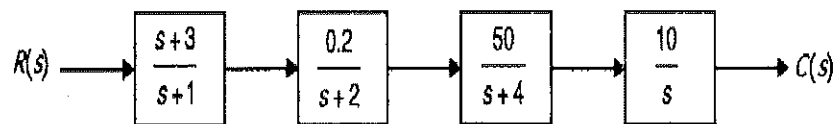
Special Requirements: Scientific Calculator, rule, pen, pencil

INSTRUCTIONS

1. Answer any **FIVE (5)** questions
2. The question paper contains **SEVEN (7)** questions
2. Each question carries 20 marks

OCT 2024

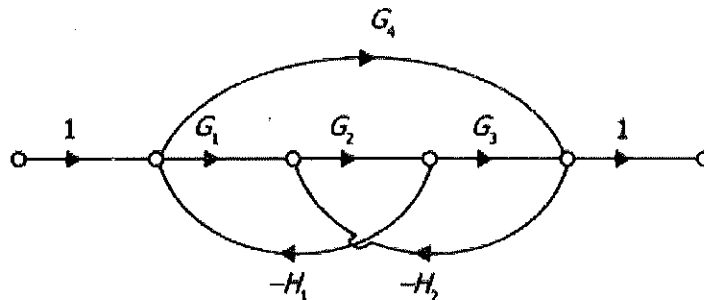
- 1(a) What is feedback. What type of feedback is employed in control system. [2]
 (b) With the aid of a block diagram state the components of a closed loop control system. [4]
 (c) State the function of each component in (a) above. [4]
 (d) Explain why negative feedback is invariably preferred in a closed loop control system. [3]
 (e) Compare and contrast open loop control system to closed loop control system. [7]
- 2(a)(i) What is the significance of standard test signals in control systems. [2]
 (ii) With the aid of mathematical equations or waveform diagram, define step input test signal. [3]
 (b) Determine the ratio $\frac{C(s)}{R(s)}$ of the block diagram shown below. [3]



- (c) Sketch the polar plot for the control system having the transfer function. [12]

$$G(s) = \frac{1}{(1+0.1s)}$$

- 3(a) Find the transfer function of the system shown in Fig. below using Mason's gain formula. [8]



- (b) With the aid of diagrams define the following Signal Flow Rules [2]
 (i) Addition Rule [2]
 (ii) Transmission rule [2]
 (iii) Multiplication Rule [2]
 (c) Find Laplace Transform of $\sin \omega t$ [6]
- 4(a) Discuss the following basic elements of Signal Flow graph (SFG) with the aid of diagrams [2]
 (i) Feedback loop [2]
 (ii) Self-loop [2]

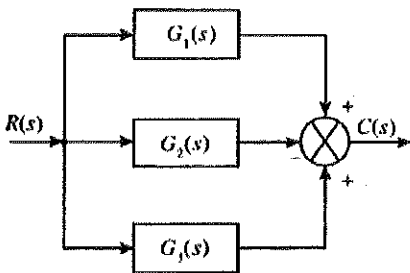
- (iii) Path gain
(iv) Non Touching loops

[2]

[2]

(b)(i) For the three connected as shown below, show that $\frac{C(s)}{R(s)} = G_1(s) - G_2(s) + G_3(s)$.

[4]



(i) Draw the equivalent block diagram.

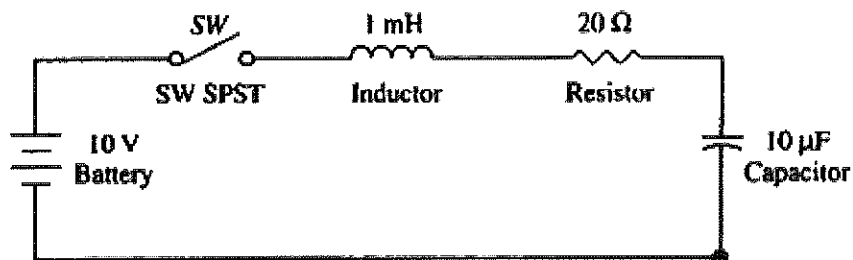
[2]

(c) A resistor, capacitor, and inductor are connected in series. A dc voltage of 10 V is applied through a battery with low internal impedance. The current i in the circuit is given by the following differential equation:

$$v = L \frac{di}{dt} + Ri + \frac{1}{C} \int_0^1 i dt$$

All initial conditions are zero; that is, at time $t = 0$, there is no magnetic field across the inductor, no charge on the capacitor, and no current through the resistor. Determine a general expression for current, which is valid for all values of time greater than or equal to 0 s. Below is the circuit diagram.

[6]



5(a) Determine the poles and zeros of the closed-loop system.

[5]

$$G_1(s) = \frac{0.1s+1}{s}, \quad G_2(s) = \frac{s+1}{s^2+2s+4}$$

(b) Determine the characteristic equation of the following system:

[2]

$$G(s) = \frac{12}{s(s^2+4s+2)} \text{ and } H(s) = 0.5$$

(c) State Routh Stability Criterion.

[2]

(d) Examine the stability of $s^5 + 6s^4 + 3s^3 + 2s^2 + s + 1 = 0$ using Routh Stability Criterion. [8]

(e) Find the Laplace transform of a unit step signal. [3]

6 (a) Find the error coefficients of a system having $G(s)H(s) = \frac{(s+3)}{s(1+0.60s)(1+0.35s)}$ [3]

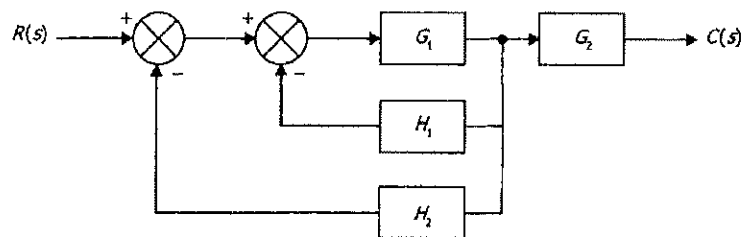
(b) Calculate the frequency response of the following system over a frequency range of 0.01 to 10 rad/s. [17]

7(a) If the transfer function of a system and applied input to it are e^{-3t} and e^{-4t} , find the response of the system. [3]

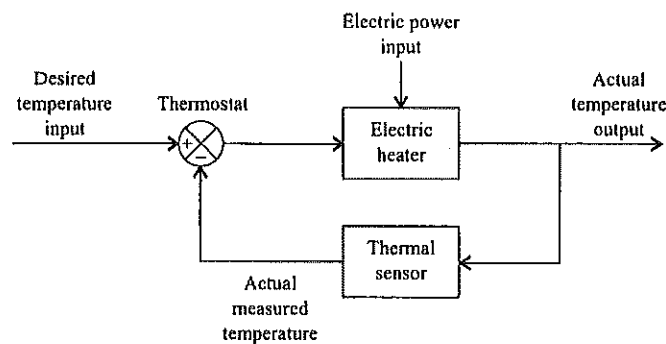
(b) What are static error constants with reference to Time Domain response. [3]

(c) A unity feedback system has an open loop transfer function of $G(s) = \frac{10}{(s+1)(s+2)}$. Determine steady state error for unit step signal input. [4]

(d) Find $C(s)/R(s)$ of the block diagram shown [6]



(e) A closed loop thermostatically controlled electric oven in the kitchen of a house is shown below. Describe its operation. [4]



The End